

Frame Theory and its Acoustical Applications

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Signal Processing
LABORATORY

Overview:

Frames in Acoustics

Peter Balazs

Frame Theory

Multipliers

Applications

Conclusions

1 Frame Theory

- Time-Frequency representation
- Non-stationary Gabor Transform

2 Frame Multipliers

3 Applications

- Perceptual Sparsity by Irrelevance
- Acoustic System Estimation

4 Conclusions

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Signal Representations: Time-Frequency Analysis and Filterbanks

Spectrogram

Frames in
Acoustics

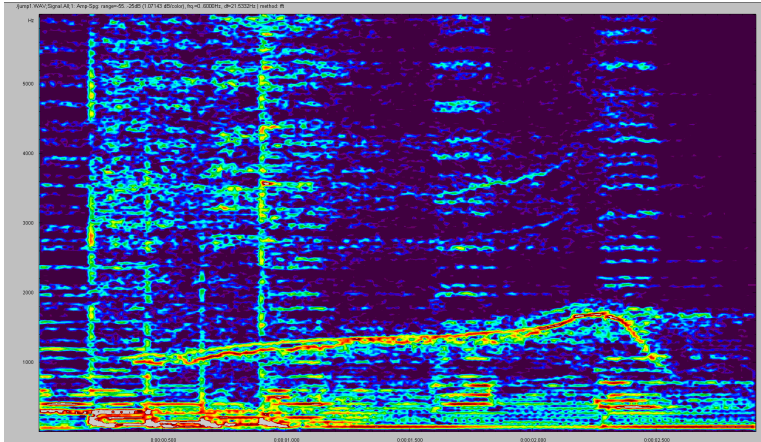
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Short Time Fourier Transformation (STFT)

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Definition (see e.g [Gröchenig, 2001])

Let $f, g \neq 0$ in $L^2(\mathbb{R}^d)$, then we call

$$\mathcal{V}_g f(\tau, \omega) = \int_{\mathbb{R}^d} f(x) \overline{g(x - \tau)} e^{-2\pi i \omega x} dx.$$

the **Short Time Fourier Transformation (STFT)** of the signal f with the window g .

$$\mathcal{V}_g(f)(\tau, \omega) = \mathcal{F}(f \cdot \overline{T_\tau g}).$$

Sampled Version: **Gabor transform** : $\tau = a \cdot k, \omega = b \cdot l$ with $k, l \in \mathbb{Z}$.

$$f \mapsto \mathcal{V}_g(f)(a \cdot k, b \cdot l).$$

When is perfect reconstruction possible?

Short Time Fourier Transformation (STFT)

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When is perfect reconstruction possible?

Filterbank

Frames in Acoustics

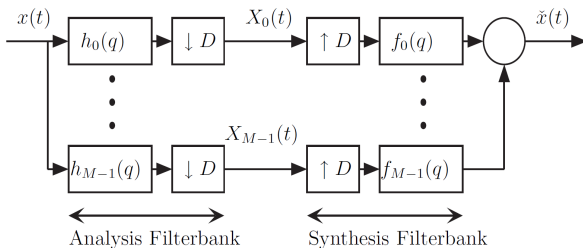
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When is perfect reconstruction possible?

Orthonormal Basis (ONB)

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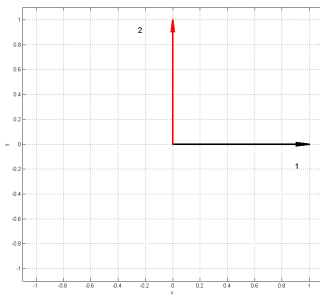
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Standard approach: orthonormal basis.



Problems:

- Perturbation
- Construction
- Error Robustness

Riesz bases

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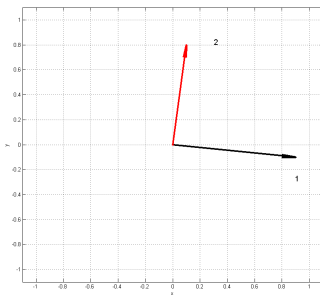
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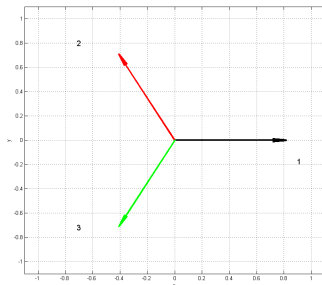
Riesz bases



Problems:

- ~~Perturbation~~
- Construction
- Error Robustness

Alternate approach: introduce redundancy.



Problems:

- Perturbation
- Construction
- Error Robustness

Definition

The (countable) sequence $\Psi = (\psi_k | k \in K)$ is called a **frame** for the Hilbert space \mathcal{H} if constants $A > 0$ and $B < \infty$ exist such that

$$A \cdot \|f\|_{\mathcal{H}}^2 \leq \sum_k |\langle f, \psi_k \rangle|^2 \leq B \cdot \|f\|_{\mathcal{H}}^2 \quad \forall f \in \mathcal{H}.$$

[Duffin and Schaeffer, 1952, Daubechies et al., 1986]

Beautiful abstract mathematical setting:

- Frames = generalization of bases; can be overcomplete, allowing redundant representations.
- Frame inequality = generalization of Parseval's condition.
- Active field of research in mathematics!

Interesting for applications:

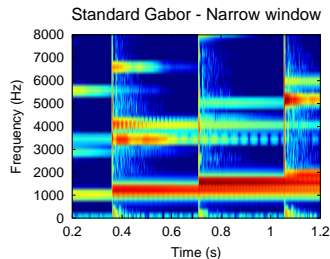
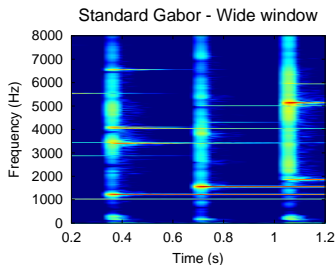
- **Much more freedom.** Finding and constructing frames can be easier and faster.
Some advantageous side constraints can **only** be fulfilled for frames.
- Perfect reconstruction is guaranteed with the 'canonical dual frame' $\tilde{\psi}_k = S^{-1}\psi_k$

$$f = \sum_k \langle f, \psi_k \rangle \tilde{\psi}_k = \sum_k \langle f, \tilde{\psi}_k \rangle \psi_k.$$

Non-stationary Gabor transform

Non-stationary Gabor transform

Limitations of Standard Gabor analysis: Quality of representation highly depends on window choice, but optimal window choice is different for different signal components



Our proposition [Balazs et al., 2011]: simple extension to reduce this limitation by using window evolving over time.

Non-stationary Gabor transform

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Given a sequence of windows $(\gamma_n)_{n \in \mathbb{Z}}$ of $L^2(\mathbb{R})$ and sequences of real numbers $(a_n)_{n \in \mathbb{Z}}$ and $(b_n)_{n \in \mathbb{Z}}$, the non-stationary Gabor transform (NSGT) elements are defined, for $(m, n) \in \mathbb{Z}^2$, by:

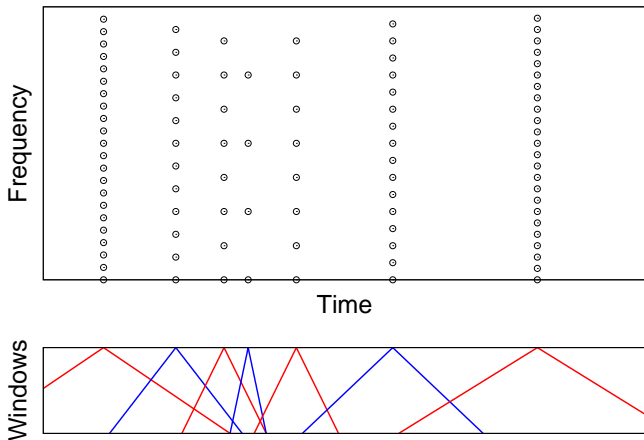
$$\gamma_{m,n}(t) = \gamma_n(t - na_n)e^{i2\pi mb_n t} = M_{mb_n} T_{na_n} \gamma_n.$$

Regular structure in frequency allows FFT implementation.

An analogue construction in the frequency domain allows easy implementation of, e.g. wavelet frames; an invertible CQT [Velasco et al., 2011]; or a filterbank adapted to human auditory perception (see talk by Thibaud Necciarì).

Non-stationary Gabor transform

Sampling grid example:



Non-stationary Gabor transform

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Frame theory allows perfect reconstruction. Especially easy and fast in the 'painless' case:

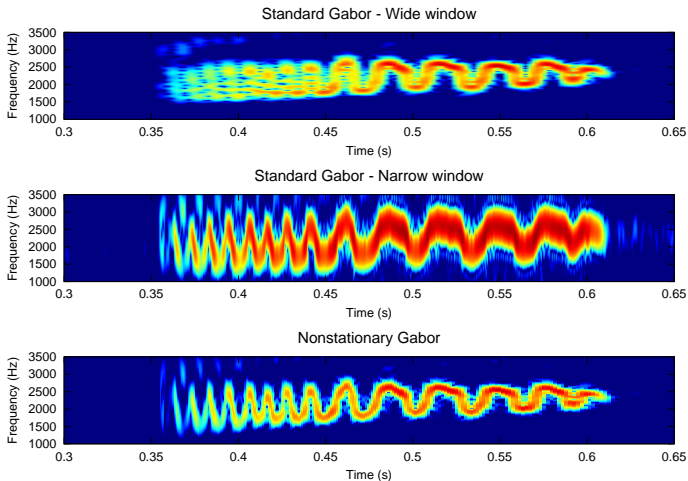
Theorem

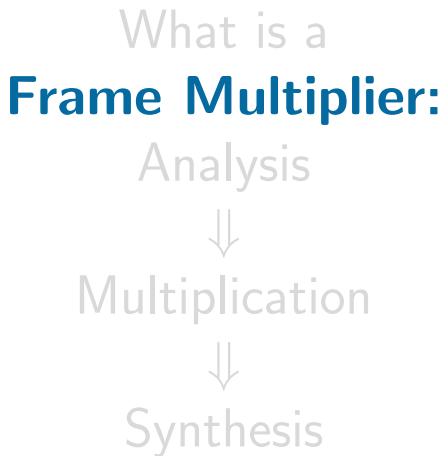
For every $n \in \mathbb{Z}$, let the function $\gamma_n \in L^2(\mathbb{R})$ be compactly supported with $\text{supp}(\gamma_n) \subseteq [c_n + na_n, d_n + na_n]$ such that $d_n - c_n \leq \frac{1}{b_n}$. the system of functions $g_{m,n}$ forms a frame for $L^2(\mathbb{R})$ if and only if there exists $A > 0$ and $B < \infty$, such that $A \leq \sum_n \frac{1}{b_n} |\gamma_n(t - na_n)|^2 \leq B$. In this case, the canonical dual frame has the same structure and is given by:

$$\tilde{\gamma}_{m,n}(t) = \frac{\gamma_n(t)}{\sum_k \frac{1}{b_k} |\gamma_k(t - ka_k)|^2} e^{2\pi i m b_n t}. \quad (1)$$

Non-stationary Gabor transform

Bird vocalization example:





What is a **Frame Multiplier:**

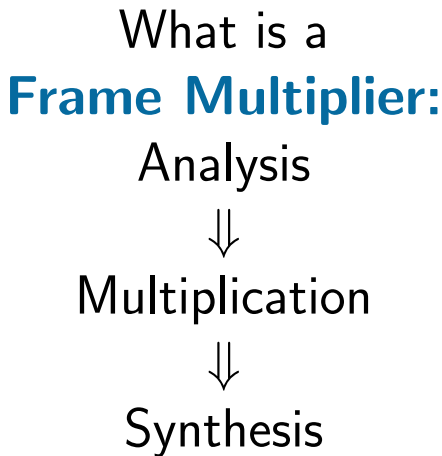
Analysis



Multiplication



Synthesis



Multipliers

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Those are operators, that are of utmost importance in

- **Mathematics**, where they are used for the diagonalization of operators [Schatten, 1960].
- **Physics**, where they are a link between classical and quantum mechanics, so called quantization operators [Ali et al., 2000].
- **Signal Processing**, where they are a particular way to implement time-variant filters [Matz and Hlawatsch, 2002].
- **Acoustics**, where those time-frequency filters are used in several fields, for example in Computational Auditory Scene Analysis [Wang and Brown, 2006].

Example for a Multiplier

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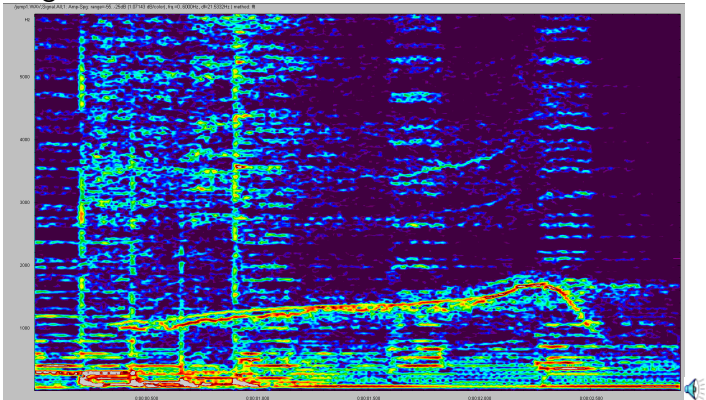
Frame Theory

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Original audio file:



Example for a Multiplier

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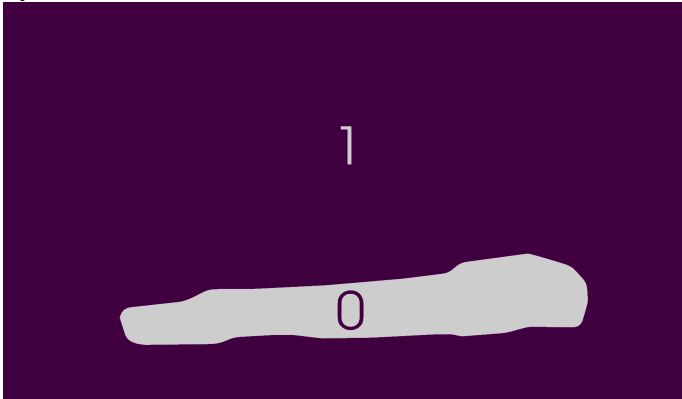
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Symbol:



Example for a Multiplier

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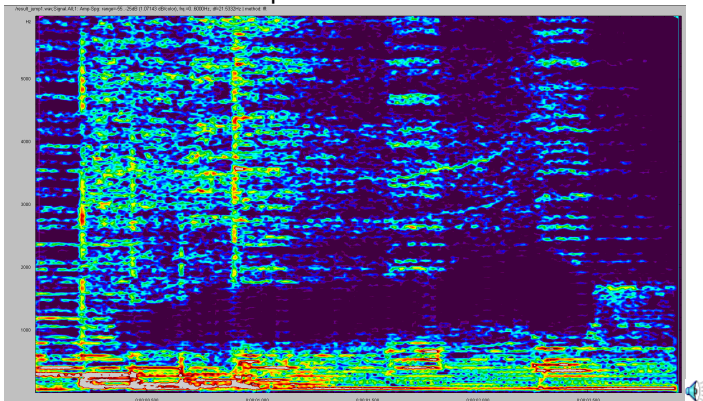
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Result of Gabor Multiplier.



Frame Multipliers: Definition

Definition

Let $(\psi_k)_{k \in K}$, $(\phi_k)_{k \in K}$ be frames in the Hilbert spaces \mathcal{H}_1 and \mathcal{H}_2 . Define the operator $\mathbf{M}_{m,(\phi_k),(\psi_k)} : \mathcal{H}_1 \rightarrow \mathcal{H}_2$, the **frame multiplier**, as the operator

$$\mathbf{M}_{m,(\phi_k),(\psi_k)} f = \sum_k m_k \langle f, \psi_k \rangle \phi_k$$

where $m \in l^\infty(K)$ is called the symbol.

Generalization of Gabor multipliers

[Feichtinger and Nowak, 2003] to the general frame case
[Balazs, 2007].

Theorem ([Balazs, 2007])

Let $\mathbf{M} = \mathbf{M}_{m,(\phi_k),(\psi_k)}$ be a frame multiplier for (ψ_k) and (ϕ_k) with the upper frame bounds B and B' respectively. Then

- 1 If $m \in l^\infty$, then \mathbf{M} is a well defined bounded operator.

$$\|\mathbf{M}\|_{Op} \leq \sqrt{B'}\sqrt{B} \cdot \|m\|_\infty.$$
- 2 $\mathbf{M}_{m,(\phi_k),(\psi_k)}^* = \mathbf{M}_{\bar{m},(\psi_k),(\phi_k)}$. Therefore if m is real-valued and $\phi_k = \psi_k$ for all k , \mathbf{M} is self-adjoint.
- 3 If $m \in c_0$, \mathbf{M} is compact.

Unconditionally Convergence and Invertibility of Frame Multipliers

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We also found sufficient conditions, when multipliers are invertible. In this case, formulas for $\mathbf{M}_{(m_n),(\phi_n),(\psi_n)}^{-1}$ are determined. For example in the following case:

Proposition ([Stoeva and Balazs, 2012])

Let $\Phi = (\phi_k)$ be a frame for \mathcal{H} . Assume that $\exists \mu \in [0, \frac{A_\Phi^2}{B_\Phi})$ such that $\sum |\langle f, m_n \psi_n - \phi_n \rangle|^2 \leq \mu \|f\|^2, \forall f \in \mathcal{H}$. Then $m\Psi$ is a frame for \mathcal{H} , the multipliers $\mathbf{M}_{\overline{m},\Phi,\Psi}$ and $\mathbf{M}_{m,\Psi,\Phi}$ are invertible on \mathcal{H} and

$$\frac{1}{B_\Phi + \sqrt{\mu B_\Phi}} \|h\| \leq \|\mathbf{M}^{-1}h\| \leq \frac{1}{A_\Phi - \sqrt{\mu B_\Phi}} \|h\|, \forall h \in \mathcal{H}, \quad (2)$$

$$\mathbf{M}^{-1} = \sum_{k=0}^{\infty} [S_\Phi^{-1}(S_\Phi - \mathbf{M})]^k S_\Phi^{-1} \quad (3)$$

where \mathbf{M} denotes any one of $\mathbf{M}_{\overline{m},\Phi,\Psi}$ and $\mathbf{M}_{m,\Psi,\Phi}$.

Numerical results and algorithms

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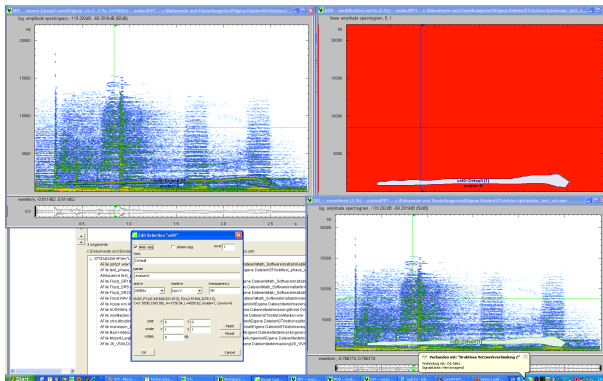
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Implementation in STx and MATLAB, in the Linear Time-Frequency Analysis Toolbox (LTFAT) [Soendergaard et al., 2012] (available at Sourceforge, see talk by Peter S ndergaard.) .

Applications in Acoustics: Perceptual Sparsity by Irrelevance

MP3-Player

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MP3:

- encoding / decoding scheme
- MPEG1/MPEG2 (Layer 3)
- signal processing
- psychoacoustical masking model

Psychoacoustic Masking: introduction

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Masking:

presence of one stimulus, the masker, decreases the response to another stimulus, the target.

Irrelevance Filter: searches (and deletes) perceptual irrelevant data (in complex signals) using a masking model.

Psychoacoustic Masking: introduction

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Perceptual Sparsity by Irrelevance

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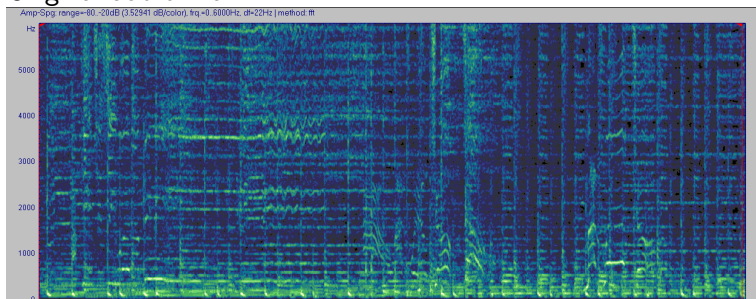
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Algorithm in :

Original audio file



Psychoacoustic Masking

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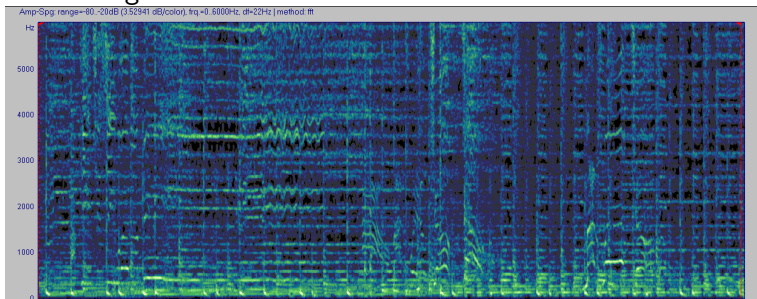
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Algorithm in 
Filtered signal



"Lossy Coding"

Perceptual Sparsity by Irrelevance

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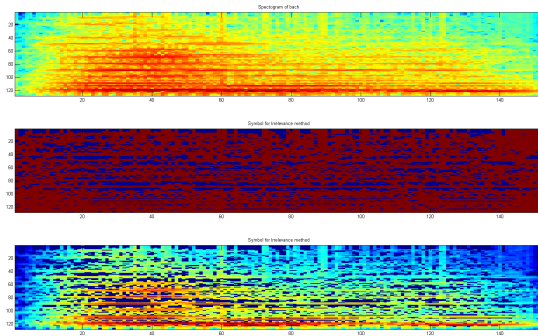
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Interpreted as adaptive Gabor frame multiplier:



Extension to True Time-Frequency Model using NSGT
Multipliers (see Talk Thibaud Necciari)

Applications in Acoustics:

Acoustic System Estimation

Acoustic System Estimation

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Measurement of Head Related Transfer Functions (HRTFs)



Acoustic System Estimation

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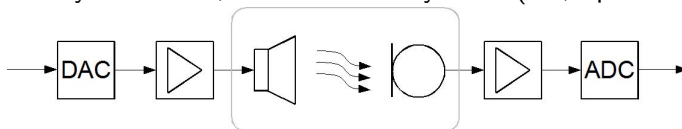
Applications

Irrelevance

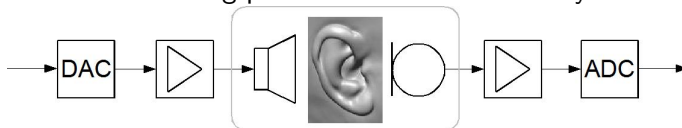
Acoustic System
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Electro-acoustic signal path:
weakly non-linear, time invariant systems (PA, Speakers)



with head-movement weakly non-linear, time variant system
But the interesting part is the HRTF: an LTI system!



Acoustic System Estimation

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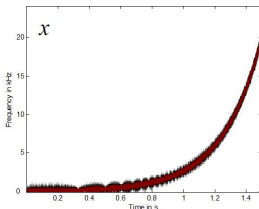
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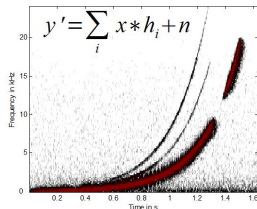
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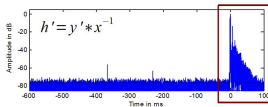
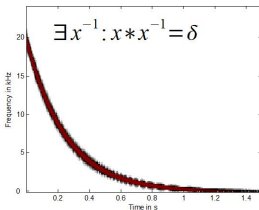
Input



Output



Deconvolution



Acoustic System Estimation

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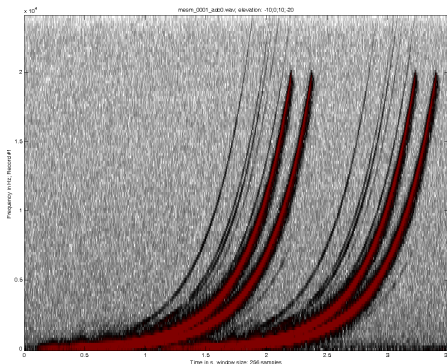
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Measurement of Head Related Transfer Functions (HRTFs) by
the Multiple Exponential Sweeps Method (MESM)
[Majdak et al., 2007]



Speed up measurement by factor of four.

Acoustic System Estimation

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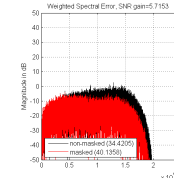
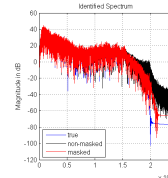
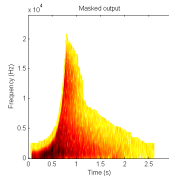
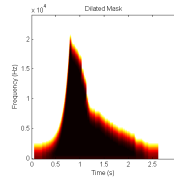
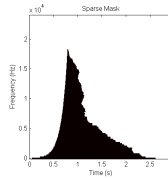
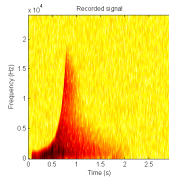
Applications

Irrelevance

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Time-Frequency Denoising [Majdak et al., 2011]:



Frames and Frame Multipliers allow

- interesting mathematical results, as well as
- provide new methods and models for acoustics, as well as their implementation.

From Theory to Applications!

Thank you for your attention!

Questions? Comments?



References: I

Frames in Acoustics

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References



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