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Computing Discrete-time Wavelet Transform Segmentwise

Pavel Rajmic

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28.10.2011

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- Segmented discrete-time wavelet transform
 - computing transform coefficients segment-by-segment

- Why? Many applications:
 - audio signal processing
 - image processing (JPEG2000)
 - parallel computing
 - DSPs (low memory capacity)...
- Generally: *Any* application requiring segmentwise processing of wavelet coefficients

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- Why? Many applications:
 - audio signal processing
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 - parallel computing
 - DSPs (low memory capacity)...
- Generally: *Any* application requiring segmentwise processing of wavelet coefficients *in an exact way*
- Introducing abbreviations SegDTWT and SegIDTWT

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• Continuous processing sample-by-sample

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- Continuous processing sample-by-sample
- Segments treated individually
 - Sharp borders
 - Windowing and overlapping
 - not suitable for nonlinear processing (e.g. thresholding), causes errors near the borders

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- Segments treated individually
 - Sharp borders
 - Windowing and overlapping
 - not suitable for nonlinear processing (e.g. thresholding), causes errors near the borders
- Segments treated in context
 - Segments are first extended by the samples from beyond their borders, then processed independently
 - Segment processes "communicate" with the others after each loop of the processing

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- Published methods belonging to the second category suffer from limitations:
 - segment length is a power of two
 - just the forward DTWT is presented (parallel compression)

- specialized to CDF 9/7 wavelet (JPEG2000)
- (segment length is fixed)

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 - segment length is a power of two
 - just the forward DTWT is presented (parallel compression)

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- specialized to CDF 9/7 wavelet (JPEG2000)
- (segment length is fixed)
- SegDTWT method gets over the limitations so that
 - s segment length,
 - m wavelet filter length,
 - J decomposition depth/level,

would be arbitrary!

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• Algorithm of one stage:

- Extend the signal's left and right borders
- Filter (lowpass, highpass)
- Cut specified number of coefficients at the borders

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• Downsample

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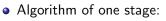
Inverse SegDTWT

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- Extend the signal's left and right borders
- Filter (lowpass, highpass)
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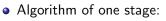
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- Cut specified number of coefficients at the borders

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Downsample

Recursion on low-band produces "tree" of coefficients

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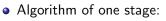
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- Extend the signal's left and right borders
- Filter (lowpass, highpass)

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• Cut specified number of coefficients at the borders

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Downsample

3

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Recursion on low-band produces "tree" of coefficients Depth J = 3:

Classic (forward) DTWT Boundary handling

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Signal is of finite length — convolution needs some samples beyond the borders!

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- number of samples?
- how to extrapolate?

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Signal is of finite length — convolution needs some samples beyond the borders!

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- number of samples?
- how to extrapolate?

We aim at the non-periodic type of border extension.

Classic (forward) DTWT — analysis

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To derive the algorithm in general setup, we need a detailed analysis of DTWT.

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Conclusion

To derive the algorithm in general setup, we need a detailed analysis of DTWT.

Given depth J and filter length m:

- How many coefficients do we compute from a given signal?
- What portion of signal do we need to compute specified coefficient(s)?
- How many such samples do the neighbouring coefficients have in common?

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- How many wavelet coefficients are affected by the concrete boundary-extrapolating samples?
- etc.

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Answers include powers of two due to downsampling.

Theorem

From signal of length s, DTWT algorithm returns

$$n_{\text{coef}}(s, m, j) = \lfloor 2^{-j}s + (1 - 2^{-j})(m - 1) \rfloor$$

wavelet coefficients at level $j \ge 1$.

Theorem

One needs

$$n_{samp}(1, j, m) = (2^j - 1)(m - 1) + 1.$$

input signal samples to compute one wavelet coefficient at j-th level.

(Forward) SegDTWT The Goal

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The goal is to compute the coefficients of the signal from its segments

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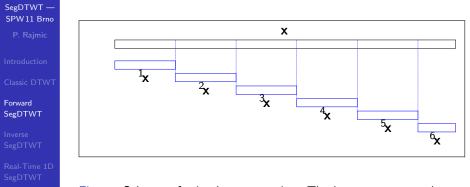
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The goal is to compute the coefficients of the signal from its segments, as if we computed it from the whole signal.

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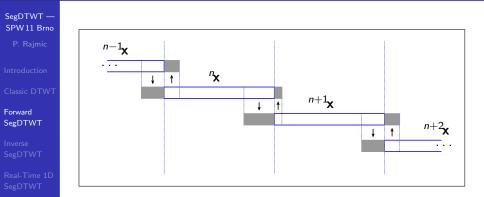
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Figure: Scheme of primal segmentation. The last segment can be shorter than others.

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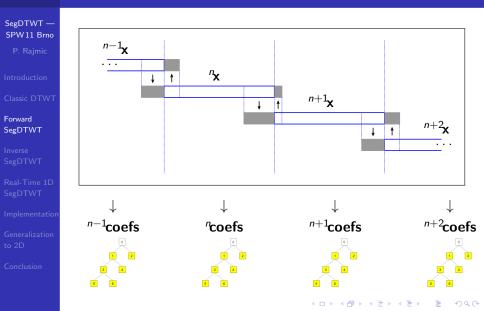
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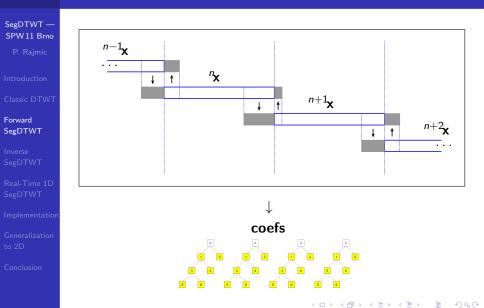
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Figure: Extending of the segments. The lengths of the individual extensions are generally not the same from one segment to another!

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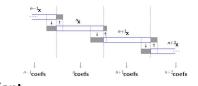
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 Problems arising from the fact that the (dyadic)
 DTWT is not shift-invariant.



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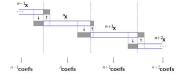
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 Problems arising from the fact that the (dyadic)
 DTWT is not shift-invariant. However, DTWT is 2^J-shift-invariant.



(Forward) SegD<u>TWT</u> Rules for the Extensions

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Forward SegDTWT

 Problems arising from the fact that the (dyadic) n-1coefs coefs DTWT is not shift-invariant.



However. DTWT is 2^J-shift-invariant.

- The right extension as small as possible introducing $R_{\min}(n), L_{\max}(n).$
- It can be shown that
 - $R_{\min}(n) = 2^J \left[\frac{ns}{2J}\right] ns$ • $L_{\max}(n+1) = (2^J - 1)(m-1) - R_{\min}(n)$
- R_{\min} is periodic, period equal to 1 achievable.

Segmented DTWT

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• For segment *n* do:

• Extend the segment with $R_{\min}(n)$, $L_{\max}(n)$

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- Filter (lowpass, highpass)
- Downsample
- Trim off redundant coefficients

Segmented DTWT Algorithm

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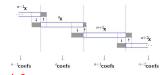
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• For J = 5, m = 8, s = 300: alternating extensions $0 \le R_{\min}(n) \le 31$, $186 \le L_{\max}(n) \le 216$, with period 8



(Forward) SegDTWT Examples

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($0 \leq$	R _r	nin(n)	\leq	31,						, 100€	fs		↓ coefs		↓ ⁿ⁺¹ coe	fs	∫ ⁿ⁺² coefs
	186		Lm	ax(n)	≤ 2	216	, v	vith	p	eric								
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	L =																		
	300	300	300	300	300	300	300	300	300	300	300	300	300	300	300	300	223		
	160 80	144 72	160 80	144 72	144 72	160 80	144 72	144 72	160 80	144 72	160 80	144 72	144 72	160 80	144 72	144 72	115 61		
	40	36	40	36	36		36	36	40	36		36	36	40	36	36			
	20	18	20	18	18	20	18	18	20	18	20	18	18	20	18	18	20		
	10	9	10	9	9	10	9	9	10	9			9	10	9	9			
	10 extension 1	9 ons = 2	10 3	9	9	10 6	9	9	10 9	9	10	9	9	10	9 15	9	13		
	217	197	209	189	201	213	193	205	217	197	209	189	201	213	193	205	217		
	20	8	28	16	4	24	12	0	20	8	28	16	4	24	12	0	294		

period =

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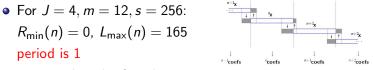
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segment length after the extension: 256 + 165 = 421.

(Forward) SegDTWT Examples

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For R _{min}			<i>'</i>			<i>′</i>					n-1	×	1	×	. †	ⁿ⁺¹ x	i + "
peri	od	is :	1								, 2 −1 co	ofe	n_	↓ oefs		↓ ¹⁺¹ coefs	
segr	ner	nt l	eng	gth	aft	er	the	e×	ktei	nsic							
>> db6_ >> [coe coefs = [1x		extens	sions,	period		egdtwt	(1:450)		, 4, d	b6_D_L		`	Lx291	double]		
L =																	
256	256	256	256	256	256	256	256	256	256	256	256	256	256	256	256	256	151
128	128	128	128	128	128	128	128	128	128	128	128	128	128	128	128	128	81
128 64	128 64	128 64	128 64	128 64	128 64	128 64	128 64	128 64	128 64	128 64	128 64	128 64	128 64	128 64	128 64	128 64	81 46
128 64 32	128 64 32	128 64 32	128 64 32	128 64 32	128 64 32	128 64 32	128 64 32	128 64 32	128 64 32	128 64 32	128 64 32	128 64 32	128 64 32	128 64 32	128 64 32	128 64 32	81 46 28
128 64	128 64	128 64	128 64	128 64	128 64	128 64	128 64	128 64	128 64	128 64	128 64	128 64	128 64	128 64	128 64	128 64	81 46
128 64 32 16	128 64 32 16 16	128 64 32 16	81 46 28 19														

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(Forward) SegDTWT Delay of the Algorithm

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The input-output delay of the forward SegDTWT is maximally one segment, in special cases even without latency!

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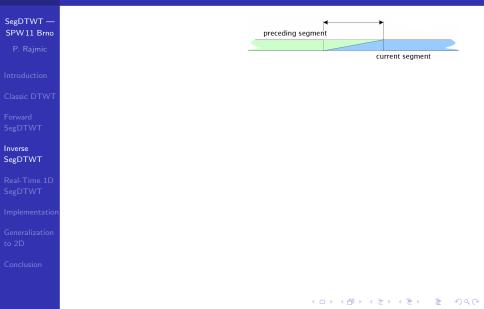
Generalizatior to 2D

Conclusion

The goal is to compute the samples of the original segments from the respective sets of wavelet coefficients.
The length of set of coefficients can differ from segment

to segment!

coe	ís =																	
	[1x]	2515 di	ouble]	[1	x1261	double]	[1x634	double]	ſ	1x320	double]		[1x163	double]	ſ	1×163	dout
ь =																		
	300	300	300	300	300	300	300	300	300	300	300	300	300	300	300	300	223	
	160	144	160	144	144	160	144	144	160	144	160	144	144	160	144	144	115	
	80	72	80	72	72	80	72	72	80	72	80	72	72	80	72	72	61	
	40	36	40	36	36	40	36	36	40	36	40	36	36	40	36	36	34	
	20	18	20	18	18	20	18	18	20	18	20	18	18	20	18	18	20	
	10	9	10	9	9	10	9	9	10	9	10	9	9	10	9	9	13	
	10	9	10	9	9	10	9	9	10	9	10	9	9	10	9	9	13	
		ons =																
ext	ensi	5115 -																
	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	
	217	197	209	189	201	213	193	205	217	197	209	189	201	213	193	205	217	
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• Length of the overlap is $(2^J - 1)(m - 1)$ samples.



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Inverse SegDTWT

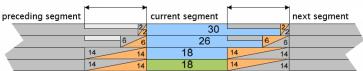
Real-Time 1D SegDTWT

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Conclusion

- Length of the overlap is $(2^J 1)(m 1)$ samples.
- Detail for J = 3, m = 3:



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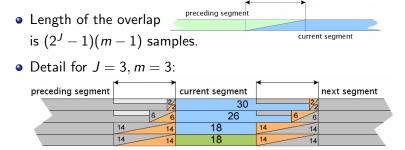
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• Length of the overlap is $(2^{J-j} - 1)(m-1)$ samples in the *j*-th level of transform.

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The Real-Time Segmented DTWT

SegDTWT — SPW11 Brno

P. Rajmic

Introduction

Classic DTWT

Forward SegDTW1

Inverse SegDTWT

Real-Time 1D SegDTWT

Implementation

Generalizatior to 2D

Conclusion

The **real-time algorithm** is created by an appropriate joining blocks from SegDTWT and SegIDTWT together, plus mechanism of interchanging the coefficients.

Implementations of 1D SegDTWT

SegDTWT — SPW11 Brno

- P. Rajmic
- Introduction
- Classic DTWT
- Forward SegDTW1
- Inverse SegDTWT
- Real-Time 1D SegDTWT

Implementation

- Generalizatioı to 2D
- Conclusion

- Matlab
- C++ offline version (command line)
- C++ VST plug-in module (real-time audio processing)
- Version presented at DAFx 2006 utilized in "Vamp Plugins" by Centre for Digital Music at Queen Mary University, London

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Generalization to 2D

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Generalization to 2D

Conclusion

- work of Zdenek Prusa
- images
- main idea is straightforward (separability)
- no "time" in an image not pushing the right extension to zero

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$\begin{array}{l} \text{Generalization to } 2D \\ \text{Example} \end{array}$



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Conclusion

$\begin{array}{l} \text{Generalization to } 2D \\ \text{Example} \end{array}$



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Conclusion

Generalization to 2D Main contributions

SegDTWT — SPW11 Brno

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- Implementation

Generalization to 2D

Conclusion

- any rectangular blocks
- Iifting scheme!
- optimization for parallel processing
- parallel implementation in C++ using Intel libraries

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P. Rajmic

Introduction

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Conclusion

• Forward and Inverse SegDTWT principles were presented

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SegDTWT — SPW11 Brno

P. Rajmic

Introduction

Classic DTWT

Forward SegDTW1

Inverse SegDTWT

Real-Time 1D SegDTWT

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• 1D and 2D

SegDTWT — SPW11 Brno

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- Introduction
- Classic DTWT
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- Inverse SegDTWT
- Real-Time 1D SegDTWT
- Implementation
- Generalizatior to 2D
- Conclusion

• Forward and Inverse SegDTWT principles were presented

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- 1D and 2D
- Fully universal (*m*, *J*, *s* arbitrary)

SegDTWT — SPW11 Brno

- P. Rajmic
- Introduction
- Classic DTWT
- Forward SegDTWT
- Inverse SegDTWT
- Real-Time 1D SegDTWT
- Implementation
- Generalizatior to 2D
- Conclusion

• Forward and Inverse SegDTWT principles were presented

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- 1D and 2D
- Fully universal (*m*, *J*, *s* arbitrary)
- Biorthogonal wavelets

SegDTWT — SPW11 Brno

P. Rajmic

Introduction

Classic DTWT

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Inverse SegDTWT

Real-Time 1D SegDTWT

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Thanks for your attention!